



Parametric Model Order Reduction

Lihong Feng

Max Planck Institute for Dynamics of Complex Technical Systems
Computational Methods in Systems and Control Theory
Magdeburg, Germany

Outline

- 1 Parametric Systems
- 2 PMOR based on multi-moment matching (Krylov subspace PMOR)
- 3 A Robust Algorithm
- 4 Conclusions

Parametric Systems

A linear parametric system

$$\begin{aligned} C(s_1, s_2, \dots, s_{p-1}) \frac{dx}{dt} &= G(s_1, s_2, \dots, s_{p-1})x + Bu(t), \\ y(t) &= L^T x, \end{aligned} \quad (1)$$

where the system matrices $C(s_1, s_2, \dots, s_{p-1})$, $G(s_1, s_2, \dots, s_{p-1})$ are (maybe, nonlinear, non-affine) functions of the parameters s_1, s_2, \dots, s_{p-1} .

PMOR based on multi-moment matching (Krylov subspace PMOR)

In frequency domain

Using Laplace transform, the system in (1) is transformed into

$$\begin{aligned} E(s_1, \dots, s_p)x &= Bu(s_p), \\ y &= L^T x, \end{aligned} \quad (2)$$

where the matrix $E \in \mathbb{R}^{n \times n}$ is parametrized. The new parameter s_p is in fact the frequency parameter s , which corresponds to time t .

In case of a nonlinear and/or non-affine dependence of the matrix E on the parameters, the system in (2) is first transformed to an affine form

$$\begin{aligned} (E_0 + \tilde{s}_1 E_1 + \tilde{s}_2 E_2 + \dots + \tilde{s}_p E_p)x &= Bu(s_p), \\ y &= L^T x. \end{aligned} \quad (3)$$

Here the newly defined parameters $\tilde{s}_i, i = 1, \dots, p$, might be some functions (rational, polynomial) of the original parameters s_i in (2).

PMOR based on multi-moment matching

To obtain the projection matrix V for the reduced model, the state x in (3) is expanded into a Taylor series at an expansion point $\tilde{s}_0 = (\tilde{s}_1^0, \dots, \tilde{s}_p^0)^T$ as below,

$$\begin{aligned}
 x &= [I - (\sigma_1 M_1 + \dots + \sigma_p M_p)]^{-1} \tilde{E}^{-1} B u(s_p) \\
 &= \sum_{m=0}^{\infty} [\sigma_1 M_1 + \dots + \sigma_p M_p]^m \tilde{E}^{-1} B u(s_p) \\
 &= \sum_{m=0}^{\infty} \sum_{k_2=0}^{m-(k_3+\dots+k_p)} \dots \sum_{k_{p-1}=0}^{m-k_p} \\
 &\quad \sum_{k_p=0}^m [F_{k_2, \dots, k_p}^m(M_1, \dots, M_p) B_M u(s_p) \sigma_1^{m-(k_2+\dots+k_p)} \sigma_2^{k_2} \dots \sigma_p^{k_p}],
 \end{aligned} \tag{4}$$

where $\sigma_i = \tilde{s}_i - \tilde{s}_i^0$, $\tilde{E} = E_0 + \tilde{s}_1^0 E_1 + \dots + \tilde{s}_p^0 E_p$, $M_i = -\tilde{E}^{-1} E_i$, $i = 1, 2, \dots, p$, and $B_M = \tilde{E}^{-1} B$. The $F_{k_2, \dots, k_p}^m(M_1, \dots, M_p)$ can be generated recursively as

PMOR based on multi-moment matching

$$F_{k_2, \dots, k_p}^m(M_1, \dots, M_p) = \begin{cases} 0, & \text{if } k_i \notin \{0, 1, \dots, m\}, i = 2, \dots, p, \\ 0, & \text{if } k_2 + \dots + k_p \notin \{0, 1, \dots, m\}, \\ I, & \text{if } m = 0, \\ M_1 F_{k_2, \dots, k_p}^{m-1}(M_1, \dots, M_p) + M_2 F_{k_2-1, \dots, k_p}^{m-1}(M_1, \dots, M_p) + \dots \\ \dots + M_p F_{k_2, \dots, k_p-1}^{m-1}(M_1, \dots, M_p), & \text{else.} \end{cases}$$

For example, if there are two parameters \tilde{s}_1, \tilde{s}_2 in (3),

$F_{k_2, \dots, k_p}^m(M_1, \dots, M_p) = F_{k_2}^m$ are:

$$F_0^0 = I,$$

$$F_0^1 = M_1 F_0^0 = M_1, \quad F_1^1 = M_2 F_0^0 = M_2 \quad (5)$$

$$F_0^2 = M_1 F_0^1 = M_1^2, \quad F_1^2 = M_1 F_1^1 + M_2 F_0^1 = M_1 M_2 + M_2 M_1, \quad F_2^2 = M_2 F_1^1 = M_2^2,$$

...

PMOR based on multi-moment-matching

For the general case, the projection matrix V is constructed as

$$\begin{aligned}
 & \text{range} \{V\} \\
 &= \text{colspan} \left\{ \bigcup_{m=0}^{m_q} \bigcup_{k_2=0}^{m-(k_p+\dots+k_3)} \dots \bigcup_{k_{p-1}=0}^{m-k_p} \bigcup_{k_p=0}^m F_{k_2, \dots, k_p}^m (M_1, \dots, M_p) B_M \right\} \\
 &= \text{colspan} \left\{ B_M, M_1 B_M, M_2 B_M, \dots, M_p B_M, (M_1)^2 B_M, (M_1 M_2 + M_2 M_1) B_M, \dots, \right. \\
 & \quad \left. (M_1 M_p + M_p M_1) B_M, (M_2)^2 B_M, (M_2 M_3 + M_3 M_2) B_M, \dots \right\}.
 \end{aligned} \tag{6}$$

We call the coefficients in the series expansion of the state x in (4) the *moment vectors* of the parametric system. The corresponding moments of the transfer function are the moment vectors multiplied by L^T from the left. For example,

PMOR based on multi-moment-matching

- $L^T B_M$: the 0th order multi-moments; the columns in B_M : the 0th order moment vectors.
- $L^T M_i B_M$, $i = 1, 2, \dots, p$: the first order multi-moments; the columns in $M_i B_M$, $i = 1, 2, \dots, p$: the first order moment vectors.
- \dots ; the columns in $M_i^2 B_M$, $i = 1, 2, \dots, p$,
 $(M_1 M_i + M_i M_1) B_M$, $i = 2, \dots, p$, $(M_2 M_i + M_i M_2) B_M$, $i = 3, \dots, p$,
 \dots , $(M_{p-1} M_p + M_p M_{p-1}) B_M$: the second order moment vectors.
- \dots

Since the coefficients corresponding not only to $s = s_p$, but also to those associated with the other parameters s_i , $i = 1, \dots, p - 1$ are, we call them as **multi-moments** of the transfer function.

A Robust Algorithm

Taking a closer look at the power series expansion of x in (4), we get the following equivalent, but different formulation,

$$\begin{aligned}
 x &= [I - (\sigma_1 M_1 + \dots + \sigma_p M_p)]^{-1} \tilde{E}^{-1} B u \\
 &= \sum_{m=0}^{\infty} [\sigma_1 M_1 + \dots + \sigma_p M_p]^m B_M u \\
 &= B_M u + [\sigma_1 M_1 + \dots + \sigma_p M_p] B_M u + [\sigma_1 M_1 + \dots + \sigma_p M_p]^2 B_M u + \dots \\
 &\quad + [\sigma_1 M_1 + \dots + \sigma_p M_p]^j B_M u + \dots
 \end{aligned} \tag{7}$$

By defining

$$\begin{aligned}
 x_0 &= B_M, \\
 x_1 &= [\sigma_1 M_1 + \dots + \sigma_p M_p] B_M, \\
 x_2 &= [\sigma_1 M_1 + \dots + \sigma_p M_p]^2 B_M, \dots, \\
 x_j &= [\sigma_1 M_1 + \dots + \sigma_p M_p]^j B_M, \dots,
 \end{aligned}$$

we have $x = (x_0 + x_1 + x_2 + \dots + x_j + \dots)u$ and obtain the recursive relations

A Robust Algorithm

$$\begin{aligned}x_0 &= B_M, \\x_1 &= [\sigma_1 M_1 + \dots + \sigma_p M_p] x_0, \\x_2 &= [\sigma_1 M_1 + \dots + \sigma_p M_p] x_1, \dots \\x_j &= [\sigma_1 M_1 + \dots + \sigma_p M_p] x_{j-1}, \dots\end{aligned}$$

If we define a vector sequence based on the coefficient matrices of x_j , $j = 0, 1, \dots$ as below,

$$\begin{aligned}R_0 &= B_M, \\R_1 &= [M_1 R_0, M_2 R_0, \dots, M_p R_0], \\R_2 &= [M_1 R_1, M_2 R_1, \dots, M_p R_1], \\&\vdots \\R_j &= [M_1 R_{j-1}, M_2 R_{j-1}, \dots, M_p R_{j-1}], \\&\vdots\end{aligned} \tag{8}$$

A Robust Algorithm

and let R be the subspace spanned by the vectors in R_j , $j = 0, 1, \dots, m$:

$$R = \text{colspan}\{R_0, \dots, R_j, \dots, R_m\},$$

then there exists $z \in \mathbb{R}^q$, such that $x \approx Vz$. Here the columns in $V \in \mathbb{R}^{n \times q}$ is a basis of R . We see that the terms in R_j , $j = 0, 1, \dots, m$ are the coefficients of the parameters in the series expansion (7). They are also the j -th order moment vectors.

How to compute an orthonormal basis V ?

Algorithm 1 Compute $V = [v_1, v_2, \dots, v_q]$

- 1: Initialize $a_1 = 0, a_2 = 0, sum = 0$.
 - 2: Compute $R_0 = \tilde{E}^{-1}B$.
 - 3: **if** (multiple input) **then**
 - 4: Orthogonalize the columns in R_0 using MGS: $[v_1, v_2, \dots, v_{q_1}] = \text{orth}\{R_0\}$ with respect to a user given tolerance $\varepsilon > 0$ specifying the deflation criterion for numerically linearly dependent vectors.
 - 5: $sum = q_1$ % q_1 is the number of columns remaining after deflation w.r.t. ε .)
 - 6: **else**
 - 7: Compute the first column in V : $v_1 = R_0 / \|R_0\|_2$
 - 8: $sum = 1$
 - 9: **end if**
 - 10: % Compute the orthonormal columns in R_1, R_2, \dots, R_m iteratively as below
-

Algorithm 2 Continued

```
1: for  $i = 1, 2, \dots, m$  do
2:    $a_2 = \text{sum}$ ;
3:   for  $t = 1, 2, \dots, p$  do
4:     IF  $a_1 = a_2$ , stop ELSE do
5:       for  $j = a_1 + 1, \dots, a_2$  do
6:          $w = \tilde{E}^{-1} E_t v_j$ ;  $\text{col} = \text{sum} + 1$ ;
7:         for  $k = 1, 2, \dots, \text{col} - 1$  do
8:            $h = v_k^T w$ ;  $w = w - h v_k$ 
9:         end for
10:        if  $\|w\|_2 > \varepsilon$  then
11:           $v_{\text{col}} = \frac{w}{\|w\|_2}$ ;  $\text{sum} = \text{col}$ ;
12:        end if
13:      end for
14:    end for
15:     $a_1 = a_2$ ;
16: end for
17: Orthogonalize the columns in  $V$  by MGS w.r.t.  $\varepsilon$ .
```

Conclusions

- PMOR methods include also reduced basis methods, which is a huge topic. The curse of dimensionality of the parameters is still unsolved.
- Other PMOR methods are not introduced: POD based method, reduced basis method, transfer function interpolation based method, PMOR based on measured data.

References

- 1 Daniel, L., Siong, O., Chay, L., Lee, K., White, J.: A multiparameter moment-matching model-reduction approach for generating geometrically parameterized interconnect performance models.
IEEE Trans. Comput.-Aided Des. Integr. Circuits Syst. **22**(5), 678–693 (2004).
- 2 Feng, L., Benner, P.: A robust algorithm for parametric model order reduction based on implicit moment matching.
Proc. Appl. Math. Mech. **7**, 1021.501–1021.502 (2008)
- 3 Peter Benner and Lihong Feng: A robust algorithm for parametric model order reduction based on implicit moment-matching.
In Reduced Order Methods for Modeling and Computational Reduction. A. Quarteroni, G. Rozza (editors), 9: 159–186, Series MS &A, 2014, Springer.